



Research Paper

## A New Block of Higher Order Hybrid Super Class BDF for Simulating Stiff IVP of ODEs

Muhammad Abdullahi<sup>1\*</sup>, G.I Danbaba<sup>2</sup>, Bashir Sule<sup>3</sup>  
<sup>1,2,3</sup>Mathematical Sciences, Federal University Dutsin-Ma, Katsina State. Nigeria

**ABSTRACT**

A new block of higher order hybrid super class of backward differentiation formula for simulating stiff IVP of ODEs was developed. The proposed new scheme can approximate the values of two point and two off-step points at a time per integration step. The scheme is Super class; it comprises a stability control parameter and by varying the value of the free parameter,  $\rho$  within the interval  $(-1, 1)$  in the formula, more zero and A-s stable schemes can be obtained. This research considers  $\rho = -\frac{3}{5}$  and arrived at zero and A – stable method, capable of solving stiff IVPs of ODEs. Approximates result from the system of stiff ODE problems considered are found to favourably validate the performance of the new method in terms of accuracy of the scale error and less executional time compared to other schemes considered in the research. Hence, the proposed new scheme (HSBDF) can be used for integrating stiff IVPs of ODEs.

**KEYWORDS:** Block, Implicit, IVPs, Ordinary Differential Equation, Zero stable

Received 06 Dec., 2022; Revised 18 Dec., 2022; Accepted 20 Dec., 2022 © The author(s) 2022.

Published with open access at [www.questjournals.org](http://www.questjournals.org)

### I. INTRODUCTION

Backward differentiation formula came to existence from the work of Curtiss & Hirschfield [1], then its extended by Cash [2 - 3], its implicit block method by Ibrahim *et al.*, [4], Super class aspect of BBDF formula by Sueiman *et al.*, [5]; Musa *et al.*, [6 - 10], diagonally implicit BBDF formula by Zawawi *et al.*, [11 - 12], Abdullahiet *al* [12 - 16], Sagiret *al* [17 - 19]. All these methods possess difference degree of accuracy when compared with some existing methods. Still due to the preferences of seeking numerical approximate solutions to most of the modern problems, numerical methods are been developed continuously with various capacities to handle current realities of stiff initial vauve problem of ODEs. A stiff equation is a differential equation for which certain numerical methods for solving the equation are numerically unstable, unless the step size is taken to be extremely small [16]. Some of the recent method with very good stability properties, at one point or the other are found with in [20 - 24]. Most of the methods stated are zero stable, A- stable or both, and displays good accuracy of the scaled error and executional time.

This research aimed at proposing a new higher order hybrid block of super class of backward differentiation formulathat possesses zeroand A- stable propertiesrequired to handle a stiff IVP of ODEs. The proposed scheme is of the form

$$\sum_{j=0}^2 \alpha_{j,i} y_{n+j-2} + \sum_{j=0}^{1+k} \alpha_{j+3,i} y_{n+(j+1)/2} = h\beta_{k+1,i} [f_{n+k} - \rho f_{n+k-2}] \quad (1)$$

where  $\rho$  is a free parameter considered with the same interval of  $(-1, 1)$  as in Musa *et al* [5]. The proposed formula (1) would be used for integrating first order stiff IVPs of the form

$$\left. \begin{aligned} y' &= f(x, \hat{Y}), \hat{Y}(a) = \varphi\eta, a \leq x \leq b \\ \text{where } \hat{Y} &= (y_1, y_2, y_3, \dots, \dots, y_n), \eta\bar{\varphi} = (\varphi\eta_1, \varphi\eta_2, \varphi\eta_3, \dots, \varphi\eta_n) \end{aligned} \right\} \quad (2)$$

### II. MATERIAL AND METHOD

In this section, two approximate solution values  $y_{n+1}$  and  $y_{n+2}$  with step size  $h$ , and two off-step points  $y_{n+\frac{1}{2}}$  and  $y_{n+\frac{3}{2}}$  which are chosen at the point where the step size are halved is formulated in a block simultaneously. The formulae are computed using the back values  $y_n, y_{n-1}$  and  $y_{n-2}$  with step size  $h$ .

From (1) consider  $k$  and  $i$  have the same value. The formula (1) is derived using Taylor's series expansion about  $x_n$

The Linear operator  $L_i$  associated with first, second, third and fourth point of the proposed formula is defined as follows

$$\left. \begin{aligned} L_i[y(x_n), h]: \alpha_{0,i}y_{n-2} + \alpha_{1,i}y_{n-1} + \alpha_{2,i}y_n + \alpha_{3,i}y_{n+\frac{1}{2}} - h\beta_{k+1,i}[f_{n+k} - \rho f_{n+k-2}] &= 0 \\ L_i[y(x_n), h]: \alpha_{0,i}y_{n-2} + \alpha_{1,i}y_{n-1} + \alpha_{2,i}y_n + \alpha_{3,i}y_{n+\frac{1}{2}} + \alpha_{4,i}y_{n+1} - h\beta_{k+1,i}[f_{n+k} - \rho f_{n+k-2}] &= 0 \\ L_i[y(x_n), h]: \alpha_{0,i}y_{n-2} + \alpha_{1,i}y_{n-1} + \alpha_{2,i}y_n + \alpha_{3,i}y_{n+\frac{1}{2}} + \alpha_{4,i}y_{n+1} + \alpha_{5,i}y_{n+\frac{3}{2}} - h\beta_{k+1,i}[f_{n+k} - \rho f_{n+k-2}] &= 0 \\ L_i[y(x_n), h]: \alpha_{0,i}y_{n-2} + \alpha_{1,i}y_{n-1} + \alpha_{2,i}y_n + \alpha_{3,i}y_{n+\frac{1}{2}} + \alpha_{4,i}y_{n+1} + \alpha_{5,i}y_{n+\frac{3}{2}} + \alpha_{6,i}y_{n+2} - h\beta_{k+1,i}[f_{n+k} - \rho f_{n+k-2}] &= 0 \end{aligned} \right\} \quad (3)$$

Consider the following value of  $k$  &  $i$ 's value in (3) for the cases below:

FOR CASE 1, 2, 3 & 4 as in  $k = i = \frac{1}{2}, k = i = 1, k = i = \frac{3}{2}$  &  $k = i = 2$  for the First, Second, Third & Fourth point respectively, with the associated operator ( $L_{\frac{1}{2}}, L_1, L_{\frac{3}{2}}$  &  $L_2$ ) related to (3) written as

$$\left. \begin{aligned} \alpha_{0,\frac{1}{2}}y(x_n - 2h) + \alpha_{1,\frac{1}{2}}y(x_n - h) + \alpha_{2,\frac{1}{2}}y(x_n) + \alpha_{3,\frac{1}{2}}y(x_n + \frac{1}{2}h) - h\beta_{\frac{1}{2}}[f(x_n + \frac{1}{2}h) + \rho f(x_n - \frac{3}{2}h)] &= 0 \\ \alpha_{0,1}y(x_n - 2h) + \alpha_{1,1}y(x_n - h) + \alpha_{2,1}y(x_n) + \alpha_{3,1}y(x_n + \frac{1}{2}h) + \alpha_{4,1}y(x_n + h) - h\beta_{1,1}[f(x_n + h) + \rho f(x_n - h)] &= 0 \\ \alpha_{0,\frac{3}{2}}y(x_n - 2h) + \alpha_{1,\frac{3}{2}}y(x_n - h) + \alpha_{2,\frac{3}{2}}y(x_n) + \alpha_{3,\frac{3}{2}}y(x_n + \frac{1}{2}h) + \alpha_{4,\frac{3}{2}}y(x_n + h) + \alpha_{5,\frac{3}{2}}y(x_n + \frac{3}{2}h) - h\beta_{\frac{3}{2}}[f(x_n + \frac{3}{2}h) + \rho f(x_n - \frac{1}{2}h)] &= 0 \\ \alpha_{0,2}y(x_n - 2h) + \alpha_{1,2}y(x_n - h) + \alpha_{2,2}y(x_n) + \alpha_{3,2}y(x_n + \frac{1}{2}h) + \alpha_{4,2}y(x_n + h) + \alpha_{5,2}y(x_n + \frac{3}{2}h) + \alpha_{6,2}y(x_n + 2h) - h\beta_{2,2}[f(x_n + 2h) + \rho f(x_n)] &= 0 \end{aligned} \right\} \quad (4)$$

Expanding  $(x_n - 2h)(x_n - h), y(x_n), y(x_n + \frac{1}{2}h), y(x_n + h), y(x_n + \frac{3}{2}h), y(x_n + 2h), f(x_n - \frac{3}{2}h), f(x_n - 2h), f_{n+2h}, f_{n+h}, f_{n+2h}$  in (4) with a Taylor's series expansion about  $x_n$  and collect the like terms gives

$$\left. \begin{aligned} C_{0,\frac{1}{2}}y(x_n) + C_{1,\frac{1}{2}}hy'(x_n) + C_{2,\frac{1}{2}}h^2y''(x_n) + \dots &= 0 \\ C_{0,1}y(x_n) + C_{1,1}hy'(x_n) + C_{2,1}h^2y''(x_n) + C_{3,1}h^3y'''(x_n) + \dots &= 0 \\ C_{0,\frac{3}{2}}y(x_n) + C_{1,\frac{3}{2}}hy'(x_n) + C_{2,\frac{3}{2}}h^2y''(x_n) + C_{3,\frac{3}{2}}h^3y'''(x_n) + C_{4,\frac{3}{2}}h^4y^{(4)}(x_n) + \dots &= 0 \\ C_{0,2}y(x_n) + C_{1,2}hy'(x_n) + C_{2,2}h^2y''(x_n) + C_{3,2}h^3y'''(x_n) + C_{4,2}h^4y^{(4)}(x_n) + \dots &= 0 \end{aligned} \right\} \quad (5)$$

Where (5) can be evaluated as in (6), (7), (8) & (9) respectively as follows

$$\left. \begin{aligned} C_{0,\frac{1}{2}} &= \alpha_{0,\frac{1}{2}} + \alpha_{1,\frac{1}{2}} + \alpha_{2,\frac{1}{2}} + \alpha_{3,\frac{1}{2}} = 0 \\ C_{1,\frac{1}{2}} &= -2\alpha_{0,\frac{1}{2}} - \alpha_{1,\frac{1}{2}} + \frac{1}{2}\alpha_{3,\frac{1}{2}} - \beta_{\frac{1}{2}}(1 - \rho) = 0 \\ C_{2,\frac{1}{2}} &= 2\alpha_{0,\frac{1}{2}} + \frac{1}{2}\alpha_{1,\frac{1}{2}} + \frac{1}{8}\alpha_{3,\frac{1}{2}} - \beta_{\frac{1}{2}}\left(\frac{1}{2} + \frac{3}{2}\rho\right) = 0 \\ C_{3,\frac{1}{2}} &= -\frac{4}{3}\alpha_{0,\frac{1}{2}} - \frac{1}{6}\alpha_{1,\frac{1}{2}} + \frac{1}{48}\alpha_{3,\frac{1}{2}} - \beta_{\frac{1}{2}}\left(\frac{1}{8} - \frac{9}{8}\rho\right) = 0 \end{aligned} \right\} \quad (6)$$

$$\left. \begin{aligned} C_{0,1} &= \alpha_{0,1} + \alpha_{1,1} + \alpha_{2,1} + \alpha_{3,1} + \alpha_{4,1} = 0 \\ C_{1,1} &= -2\alpha_{0,1} - \alpha_{1,1} + \frac{1}{2}\alpha_{3,1} + \alpha_{4,1} - \beta_{2,1}(1 - \rho) = 0 \\ C_{2,1} &= 2\alpha_{0,1} + \frac{1}{2}\alpha_{1,1} + \frac{1}{8}\alpha_{3,1} + \frac{1}{2}\alpha_{4,1} - \beta_{2,1}(1 + \rho) = 0 \\ C_{3,1} &= -\frac{4}{3}\alpha_{0,1} - \frac{1}{6}\alpha_{1,1} + \frac{1}{48}\alpha_{3,1} + \frac{1}{6}\alpha_{4,1} - \beta_{2,1}\left(\frac{1}{2} - \frac{1}{2}\rho\right) = 0 \\ C_{4,1} &= \frac{2}{3}\alpha_{0,1} + \frac{1}{24}\alpha_{1,1} + \frac{1}{384}\alpha_{3,1} + \frac{1}{24}\alpha_{4,1} - \beta_{2,1}\left(\frac{1}{6} + \frac{1}{6}\rho\right) = 0 \end{aligned} \right\} \quad (7)$$

$$\left. \begin{aligned} C_{0,\frac{3}{2}} &= \alpha_{0,\frac{3}{2}} + \alpha_{1,\frac{3}{2}} + \alpha_{2,\frac{3}{2}} + \alpha_{3,\frac{3}{2}} + \alpha_{4,\frac{3}{2}} + \alpha_{5,\frac{3}{2}} = 0 \\ C_{1,\frac{3}{2}} &= -2\alpha_{0,\frac{3}{2}} - \alpha_{1,\frac{3}{2}} + \frac{1}{2}\alpha_{3,\frac{3}{2}} + \alpha_{4,\frac{3}{2}} + \frac{3}{2}\alpha_{5,\frac{3}{2}} - \beta_{\frac{3}{2}}(1 - \rho) = 0 \\ C_{2,\frac{3}{2}} &= 2\alpha_{0,\frac{3}{2}} + \frac{1}{2}\alpha_{1,\frac{3}{2}} + \frac{1}{8}\alpha_{3,\frac{3}{2}} + \frac{1}{2}\alpha_{4,\frac{3}{2}} + \frac{9}{8}\alpha_{5,\frac{3}{2}} - \beta_{\frac{3}{2}}\left(\frac{3}{2} + \frac{1}{2}\rho\right) = 0 \\ C_{3,\frac{3}{2}} &= -\frac{4}{3}\alpha_{0,\frac{3}{2}} - \frac{1}{6}\alpha_{1,\frac{3}{2}} + \frac{1}{48}\alpha_{3,\frac{3}{2}} + \frac{1}{6}\alpha_{4,\frac{3}{2}} + \frac{27}{48}\alpha_{5,\frac{3}{2}} - \beta_{\frac{3}{2}}\left(\frac{9}{8} - \frac{1}{8}\rho\right) = 0 \\ C_{4,\frac{3}{2}} &= \frac{2}{3}\alpha_{0,\frac{3}{2}} + \frac{1}{24}\alpha_{1,\frac{3}{2}} + \frac{1}{384}\alpha_{3,\frac{3}{2}} + \frac{1}{24}\alpha_{4,\frac{3}{2}} + \frac{81}{384}\alpha_{5,\frac{3}{2}} - \beta_{\frac{3}{2}}\left(\frac{27}{48} + \frac{1}{48}\rho\right) = 0 \\ C_{5,\frac{3}{2}} &= -\frac{4}{15}\alpha_{0,\frac{3}{2}} - \frac{1}{120}\alpha_{1,\frac{3}{2}} + \frac{1}{3840}\alpha_{3,\frac{3}{2}} + \frac{1}{120}\alpha_{4,\frac{3}{2}} + \frac{243}{3840}\alpha_{5,\frac{3}{2}} - \beta_{\frac{3}{2}}\left(\frac{81}{384} - \frac{1}{384}\rho\right) = 0 \end{aligned} \right\} \quad (8)$$

&

$$\left. \begin{aligned}
 C_{0,2} &= \alpha_{0,2} + \alpha_{1,2} + \alpha_{2,2} + \alpha_{3,2} + \alpha_{4,2} + \alpha_{5,2} + \alpha_{6,2} = 0 \\
 C_{1,2} &= -2\alpha_{0,2} - \alpha_{1,2} + \frac{1}{2}\alpha_{3,2} + \alpha_{4,2} + \frac{3}{2}\alpha_{5,2} + 2\alpha_{6,2} - \beta_{3,2}(1 - \rho) = 0 \\
 C_{2,2} &= 2\alpha_{0,2} + \frac{1}{2}\alpha_{1,2} + \frac{1}{8}\alpha_{3,2} + \frac{1}{2}\alpha_{4,2} + \frac{9}{8}\alpha_{5,2} + 2\alpha_{6,2} - 2\beta_{3,2} = 0 \\
 C_{3,2} &= -\frac{4}{3}\alpha_{0,2} - \frac{1}{6}\alpha_{1,2} + \frac{1}{48}\alpha_{3,2} + \frac{1}{6}\alpha_{4,2} + \frac{27}{48}\alpha_{5,2} + \frac{4}{3}\alpha_{6,2} - 2\beta_{3,2} = 0 \\
 C_{4,2} &= \frac{2}{3}\alpha_{0,2} + \frac{1}{24}\alpha_{1,2} + \frac{1}{384}\alpha_{3,2} + \frac{1}{24}\alpha_{4,2} + \frac{81}{384}\alpha_{5,2} + \frac{2}{3}\alpha_{6,2} - \frac{4}{3}\beta_{3,2} = 0 \\
 C_{5,2} &= -\frac{4}{15}\alpha_{0,2} - \frac{1}{120}\alpha_{1,2} + \frac{1}{3840}\alpha_{3,2} + \frac{1}{120}\alpha_{4,2} + \frac{243}{3840}\alpha_{5,2} + \frac{4}{15}\alpha_{6,2} - \frac{2}{3}\beta_{3,2} = 0 \\
 C_{6,2} &= \frac{4}{45}\alpha_{0,2} + \frac{1}{720}\alpha_{1,2} + \frac{1}{46080}\alpha_{3,2} + \frac{1}{720}\alpha_{4,2} + \frac{729}{46080}\alpha_{5,2} + \frac{4}{45}\alpha_{6,2} - \frac{4}{15}\beta_{3,2} = 0
 \end{aligned} \right\} \quad (9)$$

Normalizing the Coefficients  $\alpha_{3,2}, \alpha_{4,1}, \alpha_{5,3}$  &  $\alpha_{6,2}$  of  $y_{n+\frac{1}{2}}, y_{n+1}, y_{n+\frac{3}{2}}$  &  $y_{n+2}$  respectively to 1.

Solving equation (6), (7), (8) & (9) with the aids of Maple Software for the values of  $\alpha_{j,i}$ 's and  $\beta_{j,i}$ 's and Substituting the values in (4) gives the first, second, third & fourth point as

$$\left. \begin{aligned}
 y_{n+\frac{1}{2}} &= -\frac{3}{32}y_{n-2} + \frac{25}{16}y_{n-1} - \frac{15}{32}y_n - \frac{75}{64}hf_{n+\frac{1}{2}} + \frac{75}{64}\rho hf_{n-\frac{3}{2}} \\
 y_{n+1} &= \frac{2}{155}y_{n-2} + \frac{9}{31}y_{n-1} - \frac{36}{31}y_n + \frac{288}{155}y_{n+\frac{1}{2}} + \frac{15}{62}hf_{n+1} - \frac{15}{62}\rho hf_{n-1} \\
 y_{n+\frac{3}{2}} &= \frac{9}{2312}y_{n-2} + \frac{147}{2312}y_{n-1} + \frac{1295}{2312}y_n - \frac{483}{289}y_{n+\frac{1}{2}} + \frac{4725}{2312}y_{n+1} + \frac{525}{2312}hf_{n+\frac{3}{2}} - \frac{525}{2312}\rho hf_{n-\frac{1}{2}} \\
 y_{n+2} &= -\frac{6663}{1052555}y_{n-2} + \frac{2452}{30073}y_{n-1} - \frac{10794}{30073}y_n + \frac{209664}{150365}y_{n+\frac{1}{2}} - \frac{72228}{30073}y_{n+1} + \frac{482304}{210511}y_{n+\frac{3}{2}} + \frac{6330}{30073}hf_{n+2} + \frac{6330}{30073}\rho hf_n
 \end{aligned} \right\} \quad (10)$$

(10) is called a new block of higher order hybrid super class of BDF for solving stiff initial value problem of ordinary differential equation (HSBBDF).

### III. Analysis of the Method

In this section, order and Stability properties of the proposed method (10) will be analysed.

#### 3.1 Order of the Method

In this section, the order of the proposed methods (10) will be derived.

The proposed method (10) is equivalent to the following form

$$\begin{aligned}
 (11) \quad & \frac{3}{32}y_{n-2} - \frac{25}{16}y_{n-1} + \frac{15}{32}y_n + y_{n+\frac{1}{2}} = -\frac{75}{64}hf_{n+\frac{1}{2}} + \frac{75}{64}\rho hf_{n-\frac{3}{2}} \\
 & -\frac{2}{155}y_{n-2} - \frac{9}{31}y_{n-1} + \frac{36}{31}y_n - \frac{288}{155}y_{n+\frac{1}{2}} + y_{n+1} = \frac{15}{62}hf_{n+1} - \frac{15}{62}\rho hf_{n-1} \\
 & -\frac{9}{2312}y_{n-2} - \frac{147}{2312}y_{n-1} - \frac{1295}{2312}y_n + \frac{483}{289}y_{n+\frac{1}{2}} - \frac{4725}{2312}y_{n+1} + y_{n+\frac{3}{2}} = \frac{525}{2312}hf_{n+\frac{3}{2}} - \frac{525}{2312}\rho hf_{n-\frac{1}{2}} \\
 & \frac{6663}{1052555}y_{n-2} - \frac{2452}{30073}y_{n-1} + \frac{10794}{30073}y_n - \frac{209664}{150365}y_{n+\frac{1}{2}} + \frac{72228}{30073}y_{n+1} - \frac{482304}{210511}y_{n+\frac{3}{2}} + y_{n+2} = \frac{6330}{30073}hf_{n+2} + \frac{6330}{30073}\rho hf_n
 \end{aligned}$$

(11) Can be transforming to a general matrix form as

$$\sum_{j=0}^1 C_j^* Y_{m+j-1} = h \sum_{j=0}^1 D_j^* Y_{m+j-1}, \quad (12)$$

Where C & D are constant its coefficient matrices obtain as

$$\begin{bmatrix} 0 & 0 & 0 & -\frac{3}{32} \\ 0 & 0 & 0 & -\frac{2}{155} \\ 0 & 0 & 0 & -\frac{2312}{6663} \\ 0 & 0 & 0 & \frac{1052555}{6663} \end{bmatrix} \begin{bmatrix} y_{n-\frac{7}{2}} \\ y_{n-3} \\ y_{n-\frac{5}{2}} \\ y_{n-2} \end{bmatrix} + \begin{bmatrix} 0 & -\frac{25}{16} & 0 & \frac{15}{32} \\ 0 & -\frac{9}{31} & 0 & \frac{36}{31} \\ 0 & -\frac{147}{2312} & 0 & \frac{1295}{2312} \\ 0 & -\frac{2452}{30073} & 0 & \frac{10794}{30073} \end{bmatrix} \begin{bmatrix} y_{n-\frac{3}{2}} \\ y_{n-1} \\ y_{n-\frac{1}{2}} \\ y_n \end{bmatrix} + \begin{bmatrix} 1 & 0 & 0 & 0 \\ -\frac{288}{155} & 1 & 0 & 0 \\ \frac{483}{289} & -\frac{4725}{2312} & 1 & 0 \\ \frac{209664}{150365} & \frac{72228}{30073} & -\frac{482304}{210511} & 1 \end{bmatrix} \begin{bmatrix} y_{n+\frac{1}{2}} \\ y_{n+1} \\ y_{n+\frac{3}{2}} \\ y_{n+2} \end{bmatrix} = h \begin{bmatrix} \frac{75}{64}\rho & 0 & -\frac{1}{8} & 0 \\ 0 & -\frac{15}{62}\rho & 0 & -\frac{1}{3} \\ 0 & 0 & -\frac{525}{2312}\rho & 0 \\ 0 & 0 & 0 & \frac{6330}{30073}\rho \end{bmatrix} \begin{bmatrix} f_{n-\frac{3}{2}} \\ f_{n-1} \\ f_{n-\frac{1}{2}} \\ f_n \end{bmatrix} + h \begin{bmatrix} -\frac{75}{64} & 0 & 0 & 0 \\ 0 & \frac{15}{62} & 0 & 0 \\ 0 & 0 & \frac{525}{2312} & 0 \\ 0 & 0 & 0 & \frac{6330}{30073} \end{bmatrix} \begin{bmatrix} f_{n+\frac{1}{2}} \\ f_{n+1} \\ f_{n+\frac{3}{2}} \\ f_{n+2} \end{bmatrix} \tag{13}$$

Whereas the free parameter,  $\rho$  will be considers as  $\rho = -\frac{3}{5}$ .

$$c_0 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad c_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad c_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad c_3 = \begin{bmatrix} -\frac{3}{32} \\ -\frac{2}{155} \\ -\frac{2312}{6663} \\ \frac{1052555}{6663} \end{bmatrix} \quad c_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad c_5 = \begin{bmatrix} -\frac{25}{16} \\ -\frac{9}{31} \\ -\frac{147}{2312} \\ -\frac{2452}{30073} \end{bmatrix} \quad c_6 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad c_7 = \begin{bmatrix} \frac{15}{32} \\ \frac{36}{31} \\ \frac{1295}{2312} \\ \frac{10794}{30073} \end{bmatrix} \quad c_8 =$$

$$\begin{bmatrix} \frac{1}{288} \\ -\frac{155}{483} \\ \frac{289}{209664} \\ -\frac{150365}{209664} \end{bmatrix} \quad c_9 = \begin{bmatrix} 0 \\ 1 \\ -\frac{4725}{2312} \\ \frac{72228}{30073} \end{bmatrix} \quad c_{10} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ -\frac{482304}{210511} \end{bmatrix} \quad c_{11} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \quad d_4 = \begin{bmatrix} \frac{75}{64}\rho \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad d_5 = \begin{bmatrix} 0 \\ \frac{25}{62}\rho \\ 0 \\ 0 \end{bmatrix} \quad d_6 = \begin{bmatrix} -\frac{1}{8} \\ 0 \\ -\frac{525}{2312}\rho \\ 0 \end{bmatrix}$$

$$D_7 = \begin{bmatrix} 0 \\ -\frac{1}{3} \\ 0 \\ \frac{6330}{30073} \rho \end{bmatrix} \quad D_8 = \begin{bmatrix} \frac{75}{64} \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad D_9 = \begin{bmatrix} 0 \\ \frac{15}{62} \\ 0 \\ 0 \end{bmatrix} \quad D_{10} = \begin{bmatrix} 0 \\ 0 \\ \frac{525}{2312} \\ 0 \end{bmatrix} \quad D_{11} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \frac{6330}{30073} \end{bmatrix}$$

**Definition 3.1:** The numerical method is said to be of order p if,  $E_0 = E_1 = E_2 = \dots \dots E_p = 0$  But  $E_{q+1} \neq 0$ , where  $E_{q+1}$  is the error constant of the method and q is unique integer such that

$$E_0 = \sum_{j=0}^{11} C_j = 0$$

$$E_1 = \sum_{j=0}^{11} [jC_j - 2D_j] = 0$$

$$E_2 = \sum_{j=0}^{11} \left[ \frac{1}{2!} j^2 C_j - 2jD_j \right] = 0$$

$$E_3 = \sum_{j=0}^{11} \left[ \frac{1}{3!} j^3 C_j - 2 \frac{1}{2!} j^2 D_j \right] = 0$$

$$E_4 = \sum_{j=0}^{11} \left[ \frac{1}{4!} j^4 C_j - 2 \frac{1}{3!} j^3 D_j \right] = 0$$

$$E_5 = \sum_{j=0}^{11} \left[ \frac{1}{5!} j^5 C_j - 2 \frac{1}{4!} j^4 D_j \right] = 0$$

$$E_6 = \sum_{j=0}^{11} \left[ \frac{1}{6!} j^6 C_j - 2 \frac{1}{5!} j^5 D_j \right] = 0$$

$$E_7 = \sum_{j=0}^{11} \left[ \frac{1}{7!} j^7 C_j - 2 \frac{1}{6!} j^6 D_j \right] = 0$$

$$E_8 = \sum_{j=0}^{11} \left[ \frac{1}{8!} j^8 C_j - 2 \frac{1}{7!} j^7 D_j \right] = \begin{bmatrix} -\frac{7}{32} \\ 2 \\ \frac{155}{525} \\ \frac{2312}{4096} \\ -\frac{150365}{150365} \end{bmatrix} \neq \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Therefore, the method is of order 7, with error constant  $E_8 = \begin{bmatrix} -\frac{7}{32} \\ 2 \\ \frac{155}{525} \\ \frac{2312}{4096} \\ -\frac{150365}{150365} \end{bmatrix}$  (15)

### 3.2 Stability Analysis of the Method

In this section, we investigate the Zero and A- Stability property of the proposed method (10).

**Definition 3.1** A linear multistep method is said to be zero stable if no root of the first characteristics polynomial has modulus greater than one and that any root with modulus one is simple [5].

**Definition 3.2** A linear multistep Method is said to be an A-stable method if its stability region covers the entire negative left half-plane [5].

The stability of the method (10) can be obtained by applying the standard test equation of the form

$$y' = \lambda y \quad \lambda \text{ is a complex number, } \operatorname{Re}(\lambda) < 0 \quad (16)$$

To get the following solutions

$$\left. \begin{aligned} y_{n+\frac{1}{2}} &= -\frac{3}{32}y_{n-2} + \frac{25}{16}y_{n-1} - \frac{15}{32}y_n - \frac{75}{64}h\lambda y_{n+\frac{1}{2}} + \frac{75}{64}\rho h\lambda y_{n-\frac{3}{2}} \\ y_{n+1} &= \frac{2}{155}y_{n-2} + \frac{9}{31}y_{n-1} - \frac{36}{31}y_n + \frac{288}{155}y_{n+\frac{1}{2}} + \frac{15}{62}h\lambda y_{n+1} - \frac{15}{62}\rho h\lambda y_{n-\frac{3}{2}} \\ y_{n+\frac{3}{2}} &= \frac{9}{2312}y_{n-2} + \frac{147}{2312}y_{n-1} + \frac{1295}{2312}y_n - \frac{483}{289}y_{n+\frac{1}{2}} + \frac{4725}{2312}y_{n+1} + \frac{525}{2312}h\lambda y_{n+\frac{3}{2}} - \frac{525}{2312}\rho h\lambda y_{n-\frac{1}{2}} \\ y_{n+2} &= -\frac{6663}{1052555}y_{n-2} + \frac{2452}{30073}y_{n-1} - \frac{10794}{30073}y_n + \frac{209664}{150365}y_{n+\frac{1}{2}} - \frac{72228}{30073}y_{n+1} + \frac{482304}{210511}y_{n+\frac{3}{2}} + \frac{6330}{30073}h\lambda y_{n+2} + \frac{6330}{30073}\rho h\lambda y_n \end{aligned} \right\} \quad (17)$$

(17)

(17) Can be also be written as

$$\begin{bmatrix} 1 - \frac{75}{64}h\lambda & 0 & 0 & 0 \\ -\frac{288}{155} & 1 - \frac{15}{62}h\lambda & 0 & 0 \\ \frac{483}{289} & -\frac{4725}{2312} & 1 - \frac{525}{2312}h\lambda & 0 \\ \frac{209664}{150365} & \frac{72228}{30073} & -\frac{482304}{210511} & 1 - \frac{6330}{30073}h\lambda \end{bmatrix} \begin{bmatrix} y_{n+\frac{1}{2}} \\ y_{n+1} \\ y_{n+\frac{3}{2}} \\ y_{n+2} \end{bmatrix} = h \begin{bmatrix} \frac{75}{64}\rho h\lambda & \frac{25}{16} & 0 & -\frac{15}{32} \\ 0 & \frac{9}{31} - \frac{15}{62}\rho h\lambda & 0 & -\frac{36}{31} \\ 0 & \frac{147}{2312} & \frac{525}{2312}\rho h\lambda & \frac{1295}{2312} \\ 0 & \frac{2452}{30073} & 0 & \frac{10794}{30073} - \frac{6330}{30073}\rho h\lambda \end{bmatrix} \begin{bmatrix} y_{n-\frac{3}{2}} \\ y_{n-1} \\ y_{n-\frac{1}{2}} \\ y_n \end{bmatrix} + h \begin{bmatrix} 0 & 0 & 0 & -\frac{3}{32} \\ 0 & 0 & 0 & \frac{12}{155} \\ 0 & 0 & 0 & \frac{9}{2312} \\ 0 & 0 & 0 & -\frac{6663}{1052555} \end{bmatrix} \begin{bmatrix} y_{n-\frac{7}{2}} \\ y_{n-3} \\ y_{n-\frac{5}{2}} \\ y_{n-2} \end{bmatrix} \quad (18)$$

From (18) it follows that the coefficient matrices are given as

$$A = \begin{bmatrix} 1 - \frac{75}{64}h\lambda & 0 & 0 & 0 \\ -\frac{288}{155} & 1 - \frac{15}{62}h\lambda & 0 & 0 \\ \frac{483}{289} & -\frac{4725}{2312} & 1 - \frac{525}{2312}h\lambda & 0 \\ \frac{209664}{150365} & \frac{72228}{30073} & -\frac{482304}{210511} & 1 - \frac{6330}{30073}h\lambda \end{bmatrix}$$

$$B = \begin{bmatrix} \frac{75}{64} \rho h \lambda & \frac{25}{16} & 0 & -\frac{15}{32} \\ 0 & \frac{9}{31} - \frac{15}{62} \rho h \lambda & 0 & -\frac{36}{31} \\ 0 & \frac{147}{2312} & \frac{525}{2312} \rho h \lambda & \frac{1295}{2312} \\ 0 & \frac{2452}{30073} & 0 & \frac{10794}{30073} - \frac{6330}{30073} \rho h \lambda \end{bmatrix} \quad \&$$

$$C = \begin{bmatrix} 0 & 0 & 0 & -\frac{3}{32} \\ 0 & 0 & 0 & \frac{12}{155} \\ 0 & 0 & 0 & \frac{9}{2312} \\ 0 & 0 & 0 & -\frac{6663}{1052555} \end{bmatrix}$$

The stability polynomial of the proposed method will be computed with the aid of the Maple Software using the relation

$$\det(\lambda I - A * t^2 - B * t - C) =$$

$$\begin{aligned} & -\frac{1869328125}{137945091584} t^8 h^4 + \frac{299176875}{137945091584} t^5 h^2 + \frac{132512932125}{137945091584} t^7 h^2 + \frac{499417605}{1014302144} t^8 h \\ & - \frac{88647569325}{137945091584} t^8 h^2 + \frac{76829764095}{17243136448} t^7 h + \frac{46488988125}{275890183168} t^8 h^3 \\ & + \frac{944409375}{137945091584} t^7 h^3 + \frac{3146634315}{17243136448} t^6 h - \frac{192021975}{4756727296} t^6 h^2 \\ & + \frac{517045185}{17243136448} t^5 h + \frac{112438125}{275890183168} t^6 h^3 + t^8 - \frac{168261849}{269424007} t^7 - \frac{183982971}{269424007} t^6 \\ & + \frac{105356685}{269424007} t^5 - \frac{21527179695}{17243136448} t^6 h p - \frac{43575306075}{137945091584} t^6 h^2 p^2 + \frac{57189825}{59664832} t^7 h^2 p \\ & + \frac{19368331875}{275890183168} t^6 h^3 p^2 - \frac{40451410125}{137945091584} t^5 h^2 p^2 - \frac{79417648125}{275890183168} t^7 h^3 p \\ & - \frac{1869328125}{68972545792} t^5 h^4 p^3 - \frac{5753845125}{8621568224} t^6 h^2 p - \frac{944409375}{137945091584} t^5 h^3 p^2 \\ & + \frac{1869328125}{68972545792} t^7 h^4 p - \frac{944409375}{137945091584} t^6 h^3 p + \frac{1869328125}{137945091584} t^4 h^4 p^4 \\ & + \frac{944409375}{137945091584} t^4 h^3 p^3 + \frac{112438125}{275890183168} t^3 h^3 p^3 + \frac{13560328125}{275890183168} t^5 h^3 p^3 \\ & - \frac{960065205}{1014302144} t^7 h p - \frac{13048308315}{17243136448} t^5 h p + \frac{1197559215}{17243136448} t^4 h p \\ & + \frac{5771099475}{137945091584} t^4 h^2 p^2 - \frac{25307775}{17243136448} t^5 h^2 p - \frac{112438125}{275890183168} t^4 h^3 p^2 \\ & - \frac{299176875}{137945091584} t^3 h^2 p^2 - \frac{112438125}{275890183168} t^5 h^3 p \end{aligned}$$

(19)

Where  $h = h \lambda$ .

Substituting  $\rho = -\frac{3}{5}$  and  $h = 0$  in (19) solving for  $t$ , we have (20)

$$R(t, 0) = t^8 - \frac{168261849}{269424007} t^7 - \frac{183982971}{269424007} t^6 + \frac{105356685}{269424007} t^5 \quad (21)$$

$$t = 1, 0, 0, 0, 0, 0 - 0.8112957430 \quad \& \quad 0.5351662297$$

### 3.3 A - Stability of the proposed Method

In this section, the region for the absolute stability of the proposed method is plotted, by considering the stability polynomials (19) with  $\rho = -\frac{3}{5}$ . The set of points defined by  $t = e^{i\theta}$ ,  $0 \leq \theta \leq 2\pi$  describes the boundary of the stability region. The following stability region was the complex plot of the proposed method with the aid of Maple Software.

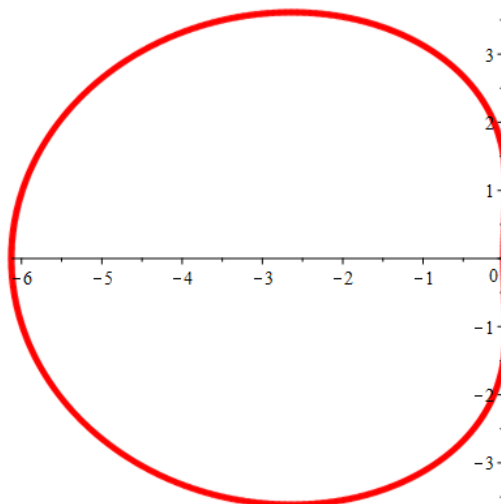


Figure 2: A-Stability region of the Proposed Method (HSBBDF)

### IV. Test Problems

To validate the method developed, the following stiff IVPs are solved.

Problem 1:  $y' = 5e^{5x}(y - x)^2 + 1$      $y(0) = 0$      $0 \leq x \leq 1$

Exact solution:

$$y(x) = x - e^{-5x}$$

Source: (Lee *et al*, 2002)

Problem 2 :  $y_1' = -20y_1 - 19y_2$      $y_1(0) = 2$   
 $y_2' = -19y_1 - 20y_2$      $y_2(0) = 0$      $0 \leq x \leq 20$

Exact Solution:

$$y_1(x) = e^{-39x} + e^{-x}$$

$$y_2(x) = e^{-39x} - e^{-x}$$

Source: (Cheney and Kincaid 2012)

Problem 3:  $y_1' = 198y_1 + 199y_2$      $y_1(0) = 1$      $0 \leq x \leq 10$   
 $y_2' = -398y_1 - 399y_2$      $y_2(0) = -1$

Exact solution

$$y_1(x) = e^{-x}$$

$$y_2(x) = -e^{-x}$$

Eigen values  $-1$  and  $-200$

Source: (Ibrahim *et al*, 2007);

### V. Result and Discussions

To validate the method developed some IVPs would be solve and the results are tabulated and compared with some existing methods. The graphs highlighting the performance of these methods are also plotted .The acronyms below are used in the tables.

**H**= step-size;

**MHTD** =Method

**MAX-ERR** = Maximum Error;

**EXE-TIME**=Executional Time in second;

**RDIBM** = A Robust Diagonally Implicit Block Method for Solving First Order Stiff IVP of ODEs

**3NBBDF** = A New Fifth Order implicit block method for Solving First Order Stiff Ordinary Differential Equations



**3ESBDF** =Extended 3-Point Super Class Of Block Backward Differentiation Formula For Solving Stiff Initial Value Problems

**3BDF**= Implicit r-point block backward differentiation formula for solving first-order stiff ODEs

**HSBDF** = A Block of Higher Order Hybrid Super Class BDF for Integrating Stiff IVP of ODEs

**Table 5.1: Comparison of Errors for Problem 1**

<i>h</i>	Mtd	NS	Max-err	Exec-Time
$10^{-2}$	3NBDF	333	3.51456(-3)	5.52416(-4)
	RDIBM	555	2.61015(-3)	3.11121(-5)
	HSBDF	100	2.22716(-5)	1.32053(-5)
	3ESBDF	333	4.83217(-3)	6.23441(-5)
$10^{-3}$	3NBDF	3,333	4.90191(-5)	4.50367(-3)
	RDIBM	5,555	3.73116(-5)	2.96482(-4)
	HSBDF	1,000	2.23872(-7)	2.10521(-3)
	3ESBDF	3,333	5.95338(-5)	6.65467(-4)
$10^{-4}$	3NBDF	33,333	5.20417(-7)	4.36918(-2)
	RDIBM	55,555	3.73371(-7)	2.94261(-3)
	HSBDF	10,000	2.24942(-9)	2.20813(-3)
	3ESBDF	33,333	5.95692(-7)	6.48433(-3)
$10^{-5}$	3NBDF	333,333	5.25030(-9)	4.34808(-1)
	RDIBM	555,555	3.73652(-9)	2.92149(-2)
	HSBDF	100,000	2.46821(-11)	2.27160(-2)
	3ESBDF	333,333	5.959740(-9)	6.58687(-2)
$10^{-6}$	3NBDF	3,333,333	5.25648(-11)	4.35791(+0)
	RDIBM	5,555,555	4.05313(-11)	2.90945(-1)
	HSBDF	1,000,000	2.48213(-13)	2.32751(-1)
	3ESBDF	3,333,333	6.186362(-11)	6.23434(-1)

**Table 5.2: Comparison of Errors for Problem 2**

<i>h</i>	Mtd	NS	Max-err	Exec-Time
$10^{-2}$	3NBDF	333	6.98707(-2)	2.63337(-2)
	RDIBM	555	4.45713(-3)	2.41226(-2)
	HSBDF	100	3.23210(-3)	9.54381(-3)
	3ESBDF	100	8.83217(-4)	7.68676(-2)
$10^{-3}$	3NBDF	3,333	5.40956(-3)	2.60816(-1)
	RDIBM	5,555	3.74938(-5)	2.42705(-1)
	HSBDF	1,000	3.20945(-5)	4.49315(-2)
	3ESBDF	1,000	6.05338(-5)	7.64515(-1)
$10^{-4}$	3NBDF	33,333	3.08942(-5)	2.60725(+0)
	RDIBM	55,555	3.52727(-7)	2.40503(+0)
	HSBDF	10,000	3.20032(-7)	2.92755(-1)
	3ESBDF	10,000	6.26692(-6)	7.68143(-1)
$10^{-5}$	3NBDF	333,333	3.18534(-7)	2.60597(+1)
	RDIBM	555,555	3.31505(-9)	2.40064(+1)
	HSBDF	100,000	3.20019(-9)	3.63812(-1)
	3ESBDF	100,000	6.32740(-8)	7.59821(+0)
$10^{-6}$	3NBDF	3,333,333	3.19872(-9)	2.60700(+2)
	RDIBM	5,555,555	3.11313(-11)	2.40003(+2)
	HSBDF	1,000,000	3.17623(-11)	2.39636(+0)
	3ESBDF	1,000,000	6.33362(-10)	7.53567(+1)

**Table 5.3: Comparison of Errors for Problem 3**

<i>h</i>	Mtd	NS	Max-err	Exec-Time
$10^{-2}$	3NBDF	333	1.94447(-4)	1.20394(-2)
	RDIBM	555	1.52564(-4)	3.93719(-3)
	HSBDF	100	4.86193(-6)	6.51294(-4)
	3BDF	333	1.07308(-2)	31,867 $\mu$ s
$10^{-3}$	3NBDF	3,333	2.07993(-6)	1.19193(-1)
	RDIBM	5,555	1.76763(-6)	1.87573(-2)
	HSBDF	1,000	4.82038(-8)	3.72066(-3)
	3BDF	3,333	1.10060(-3)	258,361 $\mu$ s
$10^{-4}$	3NBDF	33,333	2.09995(-8)	1.19296e(0)
	RDIBM	55,555	1.79766(-8)	1.66571(-1)
	HSBDF	10,000	4.79902(-10)	3.88525 (-2)
	3BDF	33,333	1.10333(-4)	2,582,756 $\mu$ s
$10^{-5}$	3NBDF	333,333	2.10257(-8)	1.19173(1)
	RDIBM	555,555	1.82566(-8)	1.43458(0)
	HSBDF	100,000	4.75952(-12)	2.39452(-1)
	3BDF	333,333	1.10361(-5)	26,011,417 $\mu$ s
$10^{-6}$	3NBDF	3,333,333	1.41029(-11)	1.19110(2)
	RDIBM	5,555,555	1.85567(-12)	1.28786(1)
	HSBDF	1,000,000	4.72882(-14)	2.29562(+0)

From table 5.1, 5.2 & 5.3 consisting the approximates result of problem 1, 2 and 3, it has shown that the newly derived scheme, HSBDF performed better than 3BBDF, ABISBDF and 3NBBDF in terms of computational time and accuracy in problems 1, 2 and 3. However, in problem 1 and 2 the proposed scheme HSBDF competes closely with RDIBM in the scaled error with new method having a little advantage over RDIBM. While, RDIBM has good scaled error and executional time than 3BBDF, ABISBDF and 3ESBDF in problems 1, 2 and 3. However, the 3NBBDF and 3ESBDF competes closely in terms of accuracy of the scale errors in problems 1. Similarly, the accuracy of the scale errors and executional time of the proposed methods, HSBDF found to be better than all the methods compared in this research. The proposed method can be an alternative solver for first order stiff IVP of ODEs.

## VI. Conclusion

A block of higher order hybrid super class of backward differentiation formula for simulating stiff IVP of ODEs is derived. The new scheme is block and hybrid, can generate four solution values, two point and two off – step point at a time per integration step. The properties of the proposed method have been checked, the method is found to be of order 7, Zero and A Stable, capable of solving stiff IVP of ODEs. Computed and approximated result validated the performance of the method in terms of accuracy of the scale error and executional time with respect to other schemes considered in this research. Hence, the proposed method can be an alternative solver of first order system of stiff IVP of ordinary differential equations.

## References

- [1]. Curtiss C.F. and Hirschfelder J.O., Integration of Stiff Equations. Proceedings of the National Academy of Sciences. 38, 235-243, 1952
- [2]. Cash, J. R. ,On the integration of stiff systems of ODEs using extended backward differentiation formulae. *NumerischeMathematik*.34: 235-246, 1980.
- [3]. Cash, J. R. Modified extended backward differentiation formula for the numerical solution of stiff IVPs in ODE and DAEs." *Computational and Applied Mathematics* 125, 117-130, 2000.
- [4]. Ibrahim, Z. B., Othman, K., & Suleiman, M.B. Implicit r-point block backward differentiation formula for solving first- order stiff ODEs. *Applied Mathematics and Computation*, 186, 558-565. 2007.
- [5]. Suleiman, M. B., Musa, H., Ismail, F., Senu, N. & Ibrahim, Z. B. A new superclass of block backward differentiation formula for stiff ordinary differential equations. *Asian European Journal of Mathematics*, 7 (1), 1 – 17. 2014.
- [6]. Musa, H., Suleiman, M. B., Ismail, F., Senu, N., Majid and Z. A., Ibrahim, Z. B, A new fifth order implicit block method for solving first order stiff ordinary differential equations. *Malaysian Journal of Mathematicam Sciences* 8(S): 45-59. 2014.
- [7]. Musa, H., Suleiman, M. B., Senu, N., Fully implicit 3-point block extended backward differentiation formula for stiff initial value problems. *Applied Mathematical Sciences*. 6: 4211-4228, 2012.
- [8]. H. Musa, M. B. Suleiman, F. Ismail, N. Senu, and Z. B. Ibrahim, An Accurate Block Solver for Stiff Initial Value Problems. Hindawi Publishing Corporation ISRN Applied Mathematics, Article ID 567451, 10 pages <http://dx.doi.org/10.1155/2013/567451>. 2014
- [9]. Bala N. and Musa H, Convergence of the Fourth Order Variable Step Size Super Class of Block Backward Differentiation Formula for Solving Stiff Initial Value Problems. *UMYU Scientifica*, 1(1), 178 – 183. <https://doi.org/10.56919/usc.1122.023>, 2022
- [10]. H. Musa, A.M. Unwala, Extended 3 point super class of block backward differentiation formula for solving first order stiff initial value problems. *Abacus (Mathematics Science Series) Vol. 44, No 1, Aug. 2019*.
- [11]. Zawawi, I. S. M., Ibrahim, Z. B., Ismail, F. and Majid, Z. A., Diagonally implicit block backward differentiation formula for solving ODEs. *International journal of mathematics and mathematical sciences*. Article ID 767328, 2012
- [12]. I. S. MohdZawawi, Z.B. Ibrahim, K.I. Othman, Derivation of diagonally implicit block backward differentiation formulas for solving stiff initial value problems. *Math.Probl.Eng.* 2015, 1, 2015.
- [13]. Abdullahi M, Shamsuddeen Suleiman, Sagir A.M, Bashir Sule; An A-stable block integrator scheme for the solution of first order system of IVPs of ordinary differential equations. *Asian Journal of probability and statistics*. 16(4):11-28. 2022.
- [14]. Abdullahi M, Musa, H, Order and Convergence of the enhanced 3 point fully implicit super class of block backward differentiation formula for solving first order stiff initial value problems. *Fudma journal of science (FJS)*. 5(2): 442-446. 2021
- [15]. Abdullahi M, Musa, H, Enhanced 3 point fully implicit super class of block backward differentiation formula for solving first order stiff initial value problems. *Fudma journal of science (FJS)*. 5(2): 120-127. 2021
- [16]. Abdullahi M, Bashir Sule, MustaphaIsiyaku, Derivation Of 2-Point Zero Stable numerical Algorithm Of Block Backward Differentiation Formula For Solving First Order Ordinary Differential Equations. *Fudma journal of science (FJS)*. 5(2): 579-584. 2021.
- [17]. A. M. Sagir, "Numerical Treatment of Block method for the solution of Ordinary Differential Equations," *International Journal of Bioengineering and Life Science*, vol. 8, no. 2, pp. 16 – 20, 2014.
- [18]. A. M. Sagir, "On the Approximate Solution of Continuous Coefficients for Solving Third Order Ordinary Differential Equations," *International Journal of Mathematical and Computational Sciences*, vol. 8, no. 1, pp. 67-70, 2014.
- [19]. A. S. Masanawa, "An accurate Computation of Block Hybrid Method for Solving Stiff Ordinary Differential Equations," *International Organization of Scientific Research Journal of Mathematics (IOSR-JM)*, vol. 4, no. 4, pp. 18-21, 2012.
- [20]. Hira Soomro1, Nooraini Zainuddin, Hanita Daud, Joshua Sunday, Noraini Jamaludin · Abdullah Abdullah, Apriyanto Mulono, Evizal Abdul Kadir (2022); 3-Point block backward differentiation formula with an of-step point for the solutions of stiff chemical reaction problems. *Journal of Mathematical Chemistry* <https://doi.org/10.1007/s10910-022-01402-2>.
- [21]. A.A. Nasarudin, Z.B. Ibrahim, H. Rosali, On the integration of stiff ODEs using block backward differentiation formulas of order six. *Symmetry* 12(6), 952, 2020.
- [22]. O. Akinfenwa, R. Abdulganiy, B. Akinnukawe, S. Okunuga, Seventh order hybrid block method for solution of first order stiff systems of initial value problems. *J. Egypt. Math. Soc.* 28(1), 1–11 (2020)

- [23]. M.M. Khalsaraei, A. Shokri, M. Molayi, The new class of multistep multiderivative hybrid methods for the numerical solution of chemical stiff systems of first order IVPs. *J. Math. Chem.* 58(9), 1987–2012 (2020)
- [24]. H. Ramos, M.A. Rufai, A two-step hybrid block method with fourth derivatives for solving third order boundary value problems. *J. Comput. Appl. Math.* 1, 113419 (2021)
- [25]. A.M.Sagir, Abdullahi, M, A Robust Diagonally Implicit Block Method for Solving First Order Stiff IVP of ODEs. *Applied Mathematics and Computational Intelligence*. Volume 11, No.1, Dec 2022 [252-273].
- [26]. Nurfaezah Mohd Husin, Iskandar Shah Mohd Zawawi, Nooraini Zainuddin, Zarina Bibi Ibrahim, "Accuracy Improvement of Block Backward Differentiation Formulas for Solving Stiff Ordinary Differential Equations Using Modified Versions of Euler's Method," *Mathematics and Statistics*, Vol. 10, No. 5, pp. 942 - 955, 2022. DOI: 10.13189/ms.2022.100506.